# **Autonomous Agents and Multi-Agent Systems**

2007/2008

## **Laboratory 9 – Reactive Agents in Counter-Strike**

## **Objectives**

• Reactive Agents implementation

### **Exercise**

A reactive agent does not keep any internal state and its behavior is described by rules as follows: < perception $>* \rightarrow$  actuator.

From the initial platform version, build reactive agents for terrorists and counterterrorists. With respect to navigation, reactive agents **cannot use** the IWaypointNavigation interface but only the IreactiveWaypointNavigation interface, which provides information about visible waypoints.

#### 1 The rules for terrorists are as follows:

- (R1) Reached destination && Is in bomb site && Is bomber -> Plant bomb
- (R2) ~Moving && Goal waypoints are visible && Is bomber -> Move to arbitrary goal waypoint
- (R3) ~Moving -> Move to arbitrary waypoint || Turn
- (R4) Enemy is visible && Is bomber -> Fire
- (R5) Enemy is visible && ~Is bomber -> Hold && Fire

### 2. The rules for counter-terrorists are as follows:

- (R1) Armed bomb is visible && ~Close enough to bomb -> Move towards it
- (R2) Armed bomb is visible && Close enough to bomb -> Defuse it
- (R3) Hears bomb  $\rightarrow$  Aim at it (so as to facilitate seeing it)
- (R4) ~Moving && Goal waypoints are visible -> Move to arbitrary goal waypoint
- (R5) ~Moving -> Move to arbitrary waypoint || Turn
- (R6) Enemy is visible && ~Bomb is planted -> Hold && Fire
- (R7) Enemy is visible && Bomb is planted -> Fire